## **Amendments to the claims:**

(currently amended) A rotary hammer, comprising:
a main body;

an impact mechanism integrated into the main body, wherein said impact mechanism generates axial impact impulses on a tool in a working direction;

a handle that is movably supported relative to the main body; and

a vibration-shielding unit connecting the handle with the main body and having a return element that produces a spring force,

wherein the vibration-shielding unit comprises a guide device (12) for guiding a motion of the handle along a straight line in the working direction such that the handle is movable in the working direction against the spring force;

and wherein the guide device comprises two force-transmission elements which are interconnected by a connecting element and are configured to perform a scissors-type motion pivotal connection in a central region of at least one of the force-transmission elements;

wherein the return element is arranged perpendicular to the working direction and engages with each of the force-transmission elements on a side of each force-transmission element that faces the handle; and

wherein each of the force-transmission elements is supported on at least one end such that it is displaceable in a direction extending perpendicular to a direction of motion.

2.	(previously presented) The rotary hammer as recited in Claim 1, wherein the
handle	e is positioned at a distance away from the main body.
3.	(canceled)
4.	(canceled)
5.	(previously presented) The rotary hammer as recited in Claim 1, wherein the
conne	cting element (24) is located in a central region of at least one of the force-
transn	nission elements (20, 22).
6.	(canceled)
7.	(canceled)
8.	(canceled)
9.	(previously presented) The rotary hammer as recited in Claim 1, characterized by
at least one elastically deformable impact-absorption element (32).	
10.	(previously presented) The rotary hammer as recited in Claim 1, wherein the
return	element is configured as an elastically deformable impact-absorption element.
11.	(previously presented) The rotary hammer as recited in Claim 1, wherein the
return	element (30) engages with at least one force-transmission element (20, 22).
12. (	canceled)

- 13. (previously presented) The rotary hammer as recited in claim 1, wherein at least a part of a first force-transmission element (20, 22) extends in a longitudinal direction of said first force-transmission element (20, 22) over a cross-over point of said force-transmission elements (20, 22) based on a cross-over point of said force-transmission elements (20, 22), wherein said part of said first force-transmission element (20, 22) has a length which is longer than a width of one of said force-transmission elements (20, 22), wherein said width is an extension of one of said force-transmission elements (20, 22) which is perpendicular in respect to the length in the longitudinal direction of the same force-transmission element (20, 22).
- 14. (previously presented) The rotary hammer as recited in claim 1, wherein one force-transmission element (20, 22) divides the other force-transmission element (20, 22) into equal halves.
- 15. (previously presented) The rotary hammer as recited in claim 1, wherein the two force-transmission elements (20, 22) have a shape of an X.
- 16. (previously presented) The rotary hammer as recited in claim 2, wherein the distance has a value between 1 cm and 1.5 cm.
- 17. (canceled)
- 18. (previously presented) The rotary hammer as recited in claim 5, wherein a central region divides the force-transmission elements (20, 22) into equal halves.
- 19. (canceled)

- 20. (previously presented) The rotary hammer as recited in claim 1, wherein each of the force-transmission elements (20, 22) extends from a first bolt (44, 46) via a connecting element (24) to a second bolt (48, 50) which is arranged opposite to the first bolt (44, 46).
- 21. (previously presented) The rotary hammer as recited in claim 20, wherein each of the force-transmission elements (20, 22) is displaceably supported in a second bolt (48, 50), wherein said second bolt (48, 50) is engaged in a slot (54, 56).
- 22. (previously presented)The rotary hammer as recited in claim 21, wherein a limitation of a movement of a force-transmission element (20, 22) is mediated by an end (58, 60, 62, 64) of the slot (54, 56).
- 23. (previously presented) The rotary hammer as recited in claim 20, wherein one bolt (44, 48) of each force-transmission element (20, 22) is arranged at the handle and the other bolt (46, 50) of each force-transmission element (20, 22) is arranged at the main body.
- 24. (previously presented) The rotary hammer as recited in claim 21, wherein one slot (54) is arranged at the handle and the other slot (56) is arranged at the main body.
- 25. (currently amended) A rotary hammer, comprising:

a main body;

an impact mechanism integrated into the main body, wherein said impact mechanism generates axial impact impulses on a tool in a working direction;

a handle that is movably supported relative to the main body; and

a vibration-shielding unit connecting the handle with the main body and having a return element that produces a spring force;

wherein the vibration-shielding unit comprises a guide device for guiding a motion of the handle along a straight line in the working direction such that the handle is movable in the working direction against the spring force;

wherein the guide device comprises two force-transmission elements which are interconnected by a connecting element in a central region of at least one of the force-transmission elements and are configured to perform a scissors-type motion;

wherein the return element is arranged perpendicular to the working direction and engages with each of the force-transmission elements on a side of each force-transmission element that faces the handle;

wherein the force-transmission elements are pivotably supported via first bolts on at least a first end of each force-transmission element;

wherein one of the force-transmission elements is pivotably supported on the main body via one of the first bolts and the other force-transmission element is pivotably supported on the handle via one of the first bolts;

wherein each of the force-transmission elements <u>are</u> is supported on at least one a second end of each force-transmission element via in a second <u>bolts</u> belt (48, 50)

such that it <u>each second end of the force-transmission elements</u> is displaceable in a direction extending perpendicular to the direction of motion;

wherein the first end of each force-transmission element is located opposite to the second end of each force-transmission element; and

wherein said second <u>bolts are</u> <del>bolt (48, 50) is</del> displaceably engaged in <u>slots</u> a slot (54, 56); <u>and</u>

wherein one of the slots is arranged at the handle and the other slot is arranged at the main body.

## 26. (canceled)

27. (currently amended) A rotary hammer, comprising:

a main body;

an impact mechanism integrated into the main body, wherein said impact mechanism generates axial impact impulses on a tool in a working direction;

a handle that is movably supported relative to the main body; and

a vibration-shielding unit connecting the handle with the main body and having a return element that produces a spring force,

wherein the vibration-shielding unit comprises a guide device (12) for guiding a motion of the handle along a straight line in the working direction such that the handle is movable in the working direction against the spring force; and

wherein the guide device comprises two force-transmission elements which are interconnected by a connecting element and are configured to perform a scissors-type

motion pivotal connection in <u>a central region of at leas tone of the force-transmission</u> elements;;

wherein the <u>force-transmission</u> force transmitting elements intersect one another in <u>said</u> [[a]] central region and are connected with one another by said connecting element in said central region;

wherein each of the <u>force-transmission</u> force-transmitting elements have two opposite ends, and the <u>force-transmission</u> force-transmitting elements are arranged so that one of the opposite ends of the two force-transmission elements <u>is</u> are connected with the handle and the other of the two opposite ends of the two <u>force-transmission</u> force-transmitting elements <u>is</u> are connected to the main body;

wherein the return element is arranged perpendicular to the working direction and engages with each of the force-transmission elements on one of the two opposite ends of each force-transmission element that faces the handle; and

wherein each of the force-transmission elements is supported on at least one end such that it is displaceable in a direction extending perpendicular to a direction of motion.